On A Fuzzy Linear Optimization Problem

Dhaneshwar Pandey
Department of Mathematics, D.E.I. Dayalbagh, Agra-282005,INDIA
E-mail: dpdr@rediffmail.com,

Abstract

According to [8,12,13, 23], the optimization models with a linear objective function subject to fuzzy re - lation equations is decidable. Algorithms are developed to solve it. In this paper, we propose a proced ure for separating the decision variables into basic and non-basic variables .A complementary problem for the original problem has been defined .Based on the structure of the feasible domain and nature of the objective function, individual variable is restricted to become bivaued .An algorithm is proposed. Two examples are considered to explain the procedure.

Keywords: Fuzzy relation equations: feasible domain, linear function, continuous t-norm, Basic and non-basic variables.

1. Introduction

We consider the following general fuzzy linear optimization problem minimize $Z = c_1x_1 + \ldots + c_mx_m$ subject to $x \circ A = b$ (1) $0 \le x_i \le 1$ $A = [a_{ij}], 0 \le a_{ij} \le 1$, be $m \times n$ -dimensional fuzzy matrix, $b = (b_j), 0 \le b_j \le 1, j \in J$, be n-dimensional vector,

 $c = (c_1, ..., c_m) \in R^m$ be cost (or weight) vector, $x = (x_i)$, $i \in I$, be m-dimensional design vector, $I = \{1,...,m\}$ and $J = \{1,...,n\}$ be the index sets and 'o' is Sup-Tcomposition, T being a continuous t-norm . More literature on Sup- Tcomposition can be found in [2,3] .The commonly used continuous tnorms are $(i)T(a, b) = \min(a,b),$ (ii)T(a,b)=product (a, b) = a.b, (3) (iii)T (a, b) = max (0, a+b-1). (4) Let $X (A, b) = \{ x = (x_1, ..., x_m) \in$ $R^m \mid x \circ A = b, x_i \in [0,1] \forall i \in I$ be the solution set. We are interested in finding a solution vector $\mathbf{x} = (x_1, ..., x_m) \in \mathbf{X}(\mathbf{A},$ b) which satisfies the constraints $Sup - T(x_i, a_{ij}) = b_j, \forall j \in J$ and minimizes the objective function Z of (1). Now we look at the structure of X(A, b).Let $x^1, x^2 \in X(A, b)$. $x^1 \le x^2$ if and only if $x^1_i \le x^2_i \ \forall i \in I$. Thus, $(X(A, b), \leq)$ becomes a lattice. Moreover, $\hat{x} \in X(A, b)$ is called maximum solution if $x \le \hat{x}$ for all x $\in X(A, b)$. Also, $\check{x} \in X(A, b)$ is called a minimal solution, if $\bar{x} \leq x$ implies $x = \check{x}, \forall x \in X(A,b)$. When X(A, b) is non- empty, it can be

completely determined by a unique maximum and a finite number of minimal solutions [1,7,8,13]. The maximum solution can be obtained by applying the following operation:

$$\hat{x} = A \lozenge b = [\inf_{j \in J} (a_{ij} \lozenge b_j)]_i \in_I \quad (6)$$

where \Diamond is inverse operator of T. The inverse operators of (2), (3), (4) can be found in [22] as given below;

$$\mathbf{a}_{ij} \lozenge \mathbf{b}_{j} = \{ \begin{array}{c} \mathbf{1} & \text{if } \mathbf{a}_{ij} \le b_{j} \\ b_{i} & \text{if } \mathbf{a}_{ii} \ge b_{i} \end{array}$$
 (7)

$$a_{ij} \diamond b_{j} = \{ \begin{array}{c} \frac{1}{b_{j}} & \text{if } a_{ij} \leq b_{j} \\ b_{j} & \text{if } a_{ij} \geq b_{j} \end{array}$$

$$a_{ij} \diamond b_{j} = \{ \begin{array}{c} \frac{1}{b_{j}} & \text{if } a_{ij} \leq b_{j} \\ b_{j} / a_{ij} & \text{if } a_{ij} \geq b_{j} \end{array}$$

$$(8)$$

$$a_{ij} \lozenge b_j = \left\{ \begin{array}{cc} 1 & \text{if } a_{ij} \le b_j \\ & & \\ 1 - a_{ij} + b_j & \text{if } a_{ij} > b_j \end{array} \right. \tag{9}$$

Let $\bar{X}(A, b)$ be the set of all minimal solutions. The X(A,b)can be looked as X(A,b) =

$$\bigcup_{\bar{x}\in \bar{X}(A,b)} \{x\in X\mid \bar{x}\leq x\leq \hat{x}\}. (10)$$

Corollary 1. $X(A, b) \subseteq X(A, b)$. We list the following useful results established in [8,13].

Lemma 1. If $x \in X(A,b)$, then for each $j \in J$ there exists $i_0 \in I$ such that $T(x_{i0}, a_{i0j}) = b_j$ and $T(x_i,$ $a_{ij} \leq b_i$ otherwise.

Proof: Since $x \circ A = b$, we have $Sup - T(x_i, a_{ij}) = b_j \text{ for } j \in J.$

This means for each j ε J, $T(\mathbf{x}_i, \mathbf{a}_{ij}) \leq \mathbf{b}_j$.

In order to satisfy the equality there exists at least one $i \in I$, say i_0 , such that $T(x_{i0},a_{i0j})=b_j$.

Proposition 1. Let T be the continuous t-norm and a,b,x \in [0,1], then equation T(x,a) = b has a solution if and only if $b \le a$. **Definition 1.** A constraint $j_0 \in J$ is called scares or binding constraint, if for $x \in X(A, b)$ and $i \in I$, $T(x_i, b)$ $a_{ij0}) = b_{j0}$.

Definition 2. For a solution x $\in X(A, b)$ and $i_0 \in I$, x_{i0} is called *binding variable* if $T(x_{i0}, a_{i0j}) = b_j$ and $T(x_i, a_{ij}) \le b_j$, for all $i \in I$. Let $X(A, b) \neq \varphi$. Define $I_{j} = [i \in I \mid T(\hat{x}_{i}, a_{ij}) = b_{j}, a_{ij} \geq b_{j} \},$ for each $j \in J$. (11)

Lemma 2. If $X(A, b) \neq \varphi$, then $I_j \neq$ $\varphi, \forall j \in J.$

Proof: Proof is consequence of lemma 1.□

Lemma 3. If $||\mathbf{I}_{i}|| = 1$, then $\hat{x}_{i} = \mathbf{x}_{i}$ $=a_{ij} \lozenge b_j \text{ for } i \in I_j$.

Proof: Since x_i , $i \in I_j$, is the only variable that satisfies the constraint j, it can take only one value equal to \hat{x}_i , determined by (6) for $i \in I_i$ and hence the lemma.

Lemma 4. For i belonging to I_i and $I_{j'}$, $a_{ij} \lozenge b_j = a_{ij'} \lozenge b_{j'}$.

Proof: Since x_i is the only variable that satisfies the constraints j and j', i.e. $T(x_i, a_{ij}) = b_j$ and $T(x_i, a_{ij'}) =$ $b_{j'}$. Therefore, $x_i = a_{ij} \lozenge b_j = a_{ij'} \lozenge b_{j'}$. \square Solving fuzzy relation equations is an interesting topic of research[1,4 -11,13-21,23-25].Studies on fuzzy relation equations with max-Tnorm composition or generalized connectives can be found in [18] .According to Gupta and Qi [10] performance of fuzzy controllers depends upon the choice of Toperators. Pedrycz [18] provided

the existence condition for max-Tnorm composition. A guide line
for selecting appropriate connector
can be found in [24]. Extensive
literatures on fuzzy relation equations with max-min composition
[25] can be seen in [19]. Recently,
Bourke and Fisher [4] studied a
system of fuzzy relation equations
with max-product composition. An
efficient procedure for solving
fuzzy relation equations with maxproduct can be found in [13].

Fang and Li [8] made seminal study on fuzzy relation equations based on max-min composition with linear objective function. They considered two sub problems of the original problem based on positive and negative costs coeff icients. One sub problem with positive costs, after defining equivalent 0-1 integer programming problem, has been solved using branch-and-bound method with jump tracking technique. Related developments regarding this can be found in [12,15,23]. Wu et.al [23] rearranged (in increasing c and b) the structure of the linear optimization problem and computed initial upper bound for equivalent 0-1 integer programming problem of original problem. They solved the 0-1 integer programmm ing problem by backward jumptracking branch- and -bound scheme.

Solving a system of fuzzy relation equations completely is a hard

problem. The total number of minimal solutions has a combinatorial nature in terms of problem size. Further more, general branchand-bound algorithm is NP-complete. An efficient method is still required..

In this paper, we propose a procedure that takes care of the characteristics of feasible domain which shows that every variable is bounded between a minimal and the maximal values. We can reduce the problem size by removing those constraints which bound the variables(according to definition (2) Clearly, none of the variables gets increased over its maximum and gets decreased below zero (i.e. assumed minimum). These boundary values can be assigned to the variable in order to improve the value of objective function and to satisfy the functional constraints In section 2, we describe the procedure and give step by step algorithm. In section 3, we consider two numerical examples and solved by using the algorithm given in section -2. Tabular computation of algorithm is proposed. Conclusions are given in the last.

2. Solution Analysis and Algorithm

Let
$$\hat{x} \in X(A, b) \neq \phi$$
. Define $I_j = [i \in I \mid T(\hat{x}_i, a_{ij}) = b_j, a_{ij} \geq b_j],$ $\forall j \in J$ (12) $J_i = \{j \in J \mid T(\hat{x}_i, a_{ij}) = b_j, a_{ij} \geq b_j\},$ $\forall i \in I$ (13)

Notice that the non-negative variable

$$x_i \le \hat{x}_i, \ \forall i \in I$$
 (14)

has an upper bound.

We write (14) as

$$x_i = \hat{x}_i - y_i , \ \forall i \in I$$
 (15)

and refer x_i and y_i as complem entary decision variables.

Whenever

(i) $x_i = 0$, then $y_i = \hat{x}_i$, and

(ii)
$$x_i = \hat{x}_i$$
, then $y_i = 0$.

Thus, $0 \le x_i \le \hat{x}_i$ implies $0 \le y_i \le \hat{x}_i$. Rather than taking each variable $y_i \in [0, \hat{x}_i]$, we consider that the each of y_i 's takes its values from the boundary values 0 (lower bound) and/or \hat{x}_i (upper bound). This reduces the problem size, also. The original problem (1)can be defined, in terms of complementary variables, as

minimize
$$Z = Z_0 - \sum_{i=1}^{m} c_i y_i$$

subject to

$$\inf_{i \in I_{j}} -T(y_{i}, a_{ij}) = 0, \forall j \in J, \qquad (16)$$

$$y_i \in \{0, \hat{x}_i\} \quad \forall i \in I.$$

where,
$$Z_0 = \sum_{i=1}^{m} c_i \hat{x}_i$$

Lemma 5. If $a_{ij}>0$, some y_i have to become zero for solving (16).

Proof: T is continuous t-norm.

 $0 \le y_i \le \hat{x}_i$. For $i \in I_j$ and $j \in J_i$,

$$y_i = 0 \Rightarrow T(y_i, a_{ij}) = 0$$

 $\Rightarrow \inf_{i \in I_j} -T(y_i, a_{ij}) = 0.$

Again,
$$Inf_{i \in I_j} - T(y_i, a_{ij}) = 0 \Rightarrow$$

 $T(y_i, a_{ij}) = 0, \exists i \in I_i.$

some
$$i \in I_j$$
. \square
Lemma 6. If $c_i > 0$, selecting $y_i = \hat{x}_i$
improves the objective function in

Since $a_{ij} > 0$, therefore, $y_i = 0$ for

Proof:
$$Z_0 \ge Z_0 - \sum_{i=1}^m c_i y_i = Z \ge Z_0 - \sum_{i=1}^m c_i y_i = Z_0 -$$

$$\sum_{i=1}^{m} c_i \widehat{x}_i \geq \min Z... \square$$

(16).

We call yi, as leaving basic variable, if it takes the value \hat{x} , to improve Z_0 and we call it as entering non-basic variable, if it takes the value zero to satisfy the constraint(s).From (14), it is clear that the membership grade x_i of a fuzzy number can not exceed \hat{x}_i . Solution set (10) is a poset, Sanchez [21]. The objective of optimization problem is to find minimum value of Z. Intuitively, minimum Z can be achieved with maximally graded (\hat{x}) fuzzy numbers, if costs are negative, where as, at minimally graded (\bar{x}) fuzzy numbers, if costs are positive. So, the technique is to select complementary variables y_i from the boundaries 0 and \hat{x}_i so as it either improves the initial value Z_0 or satisfies the constraint(s) .Every complementary variable has to follow either of two rules; (i)Rule for selecting entering nonbasic variable, i.e.choose y_i=0 in order to satisfy the constraints of J_i..(ii)Rule for selecting leaving basic variable, i.e. choose $y_i = \hat{x}_i$ in order to improve initial Z-value.

Procedure, adopted, is to find y_{NB}^{E} and y_B^L such that $y=(y_{NB}^E, y_B^L)$ and ∀i∈I (17) $y_{NB}^{E} = \{y_i \mid \text{it satisfies the constraints} \}$ of (16) for $j \in J_i$) is the set of entering non-basic variables and $y_B^L = \{ y_i \mid y_i \notin y_{NB}^E \}$ is the set of leaving basic variables. c_{NB}^{E} and c_{B}^{L} denote the costs of variables y_{NB}^{E} and y_{B}^{L} respectively. Thus, cost vector $\mathbf{c} = (c_{NB}^E, c_R^L)$. To be practical, a $y_i \in y_{NB}^E$ is selected in such a way that it has least effect on Z-function and as well as satisfies the constraints I_i, $j \in J_i$. The following steps are involved in generating the set of entering non-basic variables.

Algorithm I

- (i)Compute the value set $V=\{ V_i | V_i = c_i \hat{x}_i \text{ for each } i \in I \}$
- (ii) Generate index set $I = \{k | V_k = \min_{i \in I} (V_i)\}$
- (iii) Define $J_k = \{j \in J \mid k \in I_i \}, \forall k \in I.$
- (iv) Construct set $\{y_k | k \in I\} \subseteq y_{NB}^E$.
- (v) Select the values for y_k , $\forall k \in I$, according to (16).
- (vi) Remove the row(s) $k \in I$ and column(s) $j \in J_k$.
- (vii) Define $\hat{I} = I \setminus I$ and $\hat{J} = J \setminus \bigcup_{k \in I} J_k$.
- (viii) Set $I \leftarrow \hat{I}$ and $J \leftarrow \hat{J}$. Go to (i).
- (ix) The generated $y_{NB}^{E} = \bigcup_{k} \{y_k \mid y_k = 0\}.$

Note: 1. Since $x_i + y_i = \hat{x}_i$, $\forall i \in I$. Structure of Ij and J_i will remain unchanged

2. If $\bar{I} = \{i \mid y_i = 0, i \in I\}$, then $\|\bar{I}\| \le \min(m,n)$.

This will help us in computing the complexity of the algorithm.

We give begin algorithm to obtain

We give basic algorithm to obtain optimal solution of the problem (1)

4. The basic algorithm

Step 1: Finding the maximum solution of system of FRE in (1). Consider the existence proposition 2 and compute \hat{x} according to (6). Compute

$$\hat{x} = A \lozenge b = [Inf(a_{ij} \lozenge b_j)]_{i \in I}$$

Step 2: Test the feasibility.

If $\hat{x}o A = b$ then feasible.

Else, infeasible and stop!

Step 3: Compute index sets. Compute

 $I_j = \{ i \in I \mid T(\hat{x}_i, a_{ij}) = b_j \}, \forall j \in J$ and $J_i = \{ j \in J \mid i \in I_i \}, \forall i \in I .$

Step 4: Problem transformation.
Transform the problem(1), given in variables x, into the problem(16) in volving complementary variable y.

Step 5: Generating entering non-basic variables.

Generate the set $y_{NB}^E = \bigcup_k \{y_k \mid$

y_k=0}, using algorithm I. Step 6: Generating leaving basic variables.

Generate the set $y_B^L = \{y_i \mid y_i \neq y_{NB}^E\}$. Set $y_i = \hat{x}_i$, $\forall y_i \in y_B^L$.

Step 7: Generating complementary variables.

Complementary decision vector $\mathbf{y}^* = (y_{NB}^E, y_B^L).$

Step 8: Generating the decision variables.

Compute the decision vector x^* , according to (15).

i.e.
$$x_i^* = \hat{x}_i - y_i^* \ \forall i \in I$$
.

Step 9: Computing optimal value of objective function.

$$\mathbf{Z}^* = \mathbf{Z}_0 - \sum_{B} c_B^L \mathbf{y}_B^L$$

5. The illustration

Following two examples are considered to illustrate the procedure. **Example1.** Solving problem (1) with t-norm (2) and inverse operator (7).

Let m = 6, n = 4,c=(3,4,1,1,-1,5), b=(0.85,0.6,0.5,0.1) and

$$\mathbf{A} = \begin{bmatrix} 0.5 & 0.2 & 0.8 & 0.1 \\ 0.8 & 0.2 & 0.8 & 0.1 \\ 0.9 & 0.1 & 0.4 & 0.1 \\ 0.3 & 0.95 & 0.1 & 0.1 \\ 0.85 & 0.1 & 0.1 & 0.1 \\ 0.4 & 0.8 & 0.1 & 0.0 \end{bmatrix}$$

Step1: Finding the maximum

solution.

 \hat{x} =(0.5,0.5,0.85,0.6,1.0,0.6). Step2: $\hat{x}o$ A = b.Solution is feasible. Step 3. Index sets I_j 's and J_i 's are I_1 ={3,5}, I_2 ={4,6}, I_3 ={1,2}, I_4 ={5}. J_1 ={3}, J_2 = {3}, J_3 = {1}, J_4 = {2}, J_5 = {1,4}, J_6 = {2}. Step 4: Transformed problem is min $Z = Z_0 - 3y_1 - 4y_2 - y_3 - y_4 + y_5 - 5y_6$, Z_0 = 6.95, subject to Inf -min (y_i , a_{ij}) = b_j , j=1,...,4.

 $y_1 \in \{0, 0.5\}, y_2 \in \{0, 0.5\}, y_3 \in \{0.0.85\}, y_4 \in \{0, 0.6\}, y_5 \in \{0, 1.0\}, y_6 \in \{0, 0.6\}.$

Step 5: Generating the set y_{NB}^{E} . This is shown via table.

	I_1	I ₂	I_3	I ₄	V
J_1	\		1		1.5
J_2			2		2.0
J_3	3				0.85
J_4		4			0.6
J_5	5			5	-1.0←
J_6		6			3.0

Minimum (V) = -1.0 corresponds to y_5 . Setting $y_5 = 0$, satisfies the constraints of $J_5 = \{1,4\}$. Remove row 5 and columns I_1 , I_4 from the table. Since J_3 becomes empty, therefore row 3 will disappear.

The next table is

	I ₂	I ₃	V
J_1	+	1	1.5
J_2		2	2.0
J_4	4		0.6←
J_6	6		3.0

Minimum (V) = 0.6 corresponds to y_4 . Setting y_4 =0 satisfies the constraint of J_4 = {2}. Removing row 4 and column I_2 from the table. The reduced table is

	I ₃	V
J_1	1	1.5←
J_2	2	2.0

Minimum (V) =1.5 corresponds to y_1 . Setting $y_1 = 0$ satisfies the constraint of $J_1 = \{3\}$.

The generated $y_{NB}^{E} = (y_1, y_4, y_5) = (0, 0, 0)$. Step 6: Generating the set y_{B}^{L} . $y_{B}^{L} = (y_2, y_3, y_6) = (0.5, 0.85, 0.6)$ Step 7: $y^* = (0, 0.5, 0.85, 0, 0, 0.6)$ Step 8: $x^* = (0.5, 0, 0, 0.6, 1.0, 0)$ Step 9: $Z^* = 6.95 - 5.85 = 1.10$. Example 2. Solving problem (1)

with t-norm (3) and inverse

operator (8). Let m = 10 and n = 8.

c = (-4, 3, 2, 3, 5, 2, 1, 2, 5, 6) b = (0.48, 0.56, 0.72, 0.56, 0.64, 0.72, 0.42, 0.64) and

A =

4 %							
0.6	0.2	0.5	0.3	0.7	0.5	0.2	0.8
0.5	0.6	0.9	0.5	8.0	0.9	0.3	0.8
0.1	0.9	0.4	0.7	0.5	0.7	0.4	0.7
0.1	0.6	0.2	0.5	0.4	0.1	0.7	0.5
0.3	0.8	0.8	0.8	0.8	0.5	0.5	0.8
0.8	0.4	0.1	0.1	0.2	0.8	0.8	0.3
0.4	0.5	0.4	0.8	0.4	0.7	0.3	0.4
0.6	0.3	0.4	0.3	0.1	0.2	0.5	0.7
0.2	0.5	0.7	0.4	0.9	0.9	0.7	0.2
0.1	0.3	0.6	0.6	0.6	0.4	0.4	0.8
_							_1

Step 1: Finding the maximum solution.

 $\bar{x} = (0.8, 0.8, 0.622, 0.6, 0.7, 0.525, 0.7, 0.8, 0.6, 0.8).$ Step 2: $\hat{x}aA = b$. Solution is feasible.

Step 3: Index sets I_j 's and J_i 's are $I_1=\{1,8\},I_2=\{3,5\},I_3=\{2\},I_4=\{5,7\},I_5=\{2\},I_6=\{2\},I_7=\{4,6,9\},I_8=\{1,2.10\}$

$$J_1 = \{1, 8\}, J_2 = \{3, 5, 6, 8\}, J_3 = \{2\}, J_4 = \{7\}, J_5 = \{2, 4\}, J_6 = \{7\}, J_7 = \{4\}, J_8 = \{1\}, J_9 = \{7\}, J_{10} = \{8\}.$$

Step 4: Problem (1) can be transformed to become min $Z = Z_0 + 4y_1 - 3y_2 - 2y_3 - 3y_4 - 5y_5 - 2y_6 - y_7 - 2y_8 - 5y_9 - 6y_{10}$, $Z_0 = 16.894$ subject to

 $\inf_{i \in J} - (y_i \cdot a_{ij}) = 0, \quad \forall j \in J$

 $y_1 \in \{0, 0.8\}, y_2 \in \{0, 0.8\}, y_3 \in \{0.0.622\}, y_4 \in \{0, 0.6\}, y_5 \in \{0, 0.7\}, y_6 \in \{0, 0.525\}, y_7 \in \{0, 0.7\}, y_8 \in \{0, 0.8\}, y_9 \in \{0.0.6\}, y_{10} \in \{0, 0.8\}.$

Step 5: Computing the set y_{NR}^{E} .

		***************************************			***********		# ND -		Maria a servicia de la casa de la
•	\mathbf{I}_1	\mathbf{I}_2	I_3	I_4	I_5	I_6	I_7	I_8	V
	1							ļ	
J_1	1							1	-3.2←
\mathbf{J}_2			2	,	2	2		2	2.4
J ₃		3							1.244
J_4	P4. / . = 1 1280	MIT - E V / JUNE 1980	Moreover automorphis	300 000 - 2020 - 6220 - 7450 - 6844	Page 1 20	ene en circom	4		1.8
J_5		5		5					3.5
J ₆							6		1.05
J ₇				7					0.7
J_8	8								1.6
J 9					1400		9		3.0
J ₁₀								10	4.8

Selecting $y_1 = 0$ satisfies the constraint of $J_1 = \{1,8\}$. After removing the rows 1,8,10 (since J_8 and J_{10} become empty) and columns 1 and 8, above table takes the following form

	I ₂	I_3	I ₄	I_5	I_6	I_7	V
J_2		2		2	2		2.4
J ₃	3						1.244
J_4						4	1.8
J_5	5		5				3.5

J_6		6	1.05
J_7	7		0.7←
J ₉		9	3.0

Setting $y_7 = 0$ satisfies the constraints of $J_7 = \{4\}$. Delete row 7 and column 4. Reduced table is

	I ₂	I_3	I_5	I ₆	I ₇	V
					\downarrow	
J_2		2	2	2		2.4
J_3	3					1.244
J_4					4	1.8
J_5	5					3.5
J_6					6	1.05←
J_9					9	3.0

Set $y_6 = 0$. This satisfies the constraints of $J_6 = \{7\}$. Deleting the corresponding rows and column, table reduces to become

	I_2	I ₃	I ₅	I ₆	V
J_2		2	2	2	2.4
J_3	3				1.244←
J_5	5				3.5

 $y_3 = 0$ satisfies the constraint of $J_3 = \{2\}$. After removing the rows and columns, above table reduces to become

	I_3	I ₅	I_6	V
	↓	1	1	
J_2	2	2	2	2.4←
L			1	

 $y_2 = 0$ satisfies all the remaining constraints of $J_2 = \{3, 5, 6\}$. $y_{NB}^E = (y_1, y_2, y_3, y_6, y_7) = (0, 0, 0, 0, 0, 0)$ Step 6: $y_B^L = (y_4, y_5, y_8, y_9, y_{10})$ = (0.6, 0.7, 0.8, 0.6, 0.8). Step 7: $y^* = (0, 0, 0, 0.6, 0.7, 0, 0, 0.8, 0.6, 0.8)$. Step 8: $x^* = (0.8, 0.8, 0.622, 0, 0, 0.525, 0.7, 0, 0, 0)$. Step 9: $Z^* = 16.894 - 14.700 = 2.194$.

6. Conclusions

This paper studies a linear optimization problem subject to a system of fuzzy relation equations and presents a procedure to find the optimal solution. Due to nonconvexity of feasible domain, traditional methods, viz, simplex method etc. can not be applied. Procedure, adopted here, finds a way of separating the set of decision variables into basic and non-basic variables and evaluates their values. Since every binding variable is bounded and has

discrete behavior, because of nonconvexity, they can assume only boundary values of the interval in which they lie. In terns, we define the complementary variables and hence the complementary optimization problem. Algorithm is developed to solve this complem entary problem. Significantly, the whole procedure can be presented in a table and time complexity is lesser.

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