

**NOTES ON CONVEX DECOMPOSITION
OF BOLD FUZZY EQUIVALENCE RELATIONS**

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Geometric properties of the convex set of bold fuzzy equivalence relations are studied in connection with a problem of decomposition into convex combination of max-min equivalence relations. Two particular combinatorial conditions of decomposability are proposed.

Keywords : extremal points, affine dimension, t-trans-convexity

1. NOTATIONS

Y - arbitrary set; $|Y|$ - cardinality of Y ;

if Y is a subset of linear space, \hat{Y} is convex hull of Y ;

dually, if Y is a convex subset of linear space, $\overset{\vee}{Y}$ denotes the set of all extremal points of Y (non-decomposable in convex combination of two different points in Y);

$\tilde{\mathcal{F}}(Y)$ - set of all fuzzy subsets of Y ;

$\dim(\cdot)$ - topological (linear, affine) dimension;

finite X , $|X|=n$ - support of all fuzzy/crisp binary relations (FRs/BRs);

\vee, \wedge - max-min operations; $\hat{\wedge}$ - bold intersection;

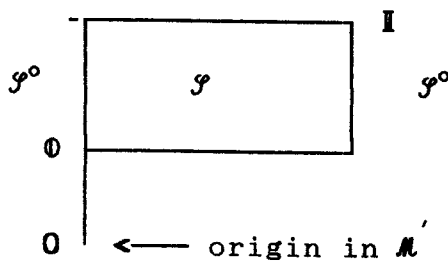
superscript \circ is used to denote crisp objects;

\mathcal{M}' - linear space of all symmetric real-valued $n \times n$ matrices with constant diagonal ($R \in \mathcal{M}' \leftrightarrow (r_{ii} = \alpha \ \& \ r_{ij} = r_{ji})$); more accurately, \mathcal{M}'_n - for brevity, subscript n is omitted in all designations);

\mathcal{S} - set of all reflexive and symmetric FRs, considered both as \vee, \wedge lattice with minimal element $\mathbf{0} = \begin{vmatrix} 1 & & 0 \\ & 1 & \\ 0 & & 1 \end{vmatrix}$, maximal ele-

ment $\mathbf{I} = \begin{vmatrix} 1 & 1 \dots 1 \\ & \dots & \\ 1 & 1 \dots 1 \end{vmatrix}$, and as $N = \frac{n(n-1)}{2}$ - dimensional affi-

ne cube $[\mathbf{0}, \mathbf{I}]$, imbedded in $(N+1)$ -dimensional linear space \mathcal{M}' ;



$\|\cdot\|_1$ - Hemming norm in \mathcal{S} : $\|R\|_1 = \sum_{i < j} e_{ij}$ (only upper triangle of a matrix is used in all considerations);

$\rho_1(E, Y) = \inf_{R \in Y} \|E - R\|_1$ - Hemming distance between a relation $E \in \mathcal{S}$ and a subset $Y \subseteq \mathcal{S}$;

$V(E, 1)$ - 1-neighborhood of E in Hemming metric, that is, intersection of \mathcal{S} with Hemming sphere of radius 1, centered in $E \in \mathcal{S}$;

\mathcal{S}^0 - crisp reflexive&symmetric relations (vertexes of \mathcal{S});

\mathfrak{E} - set of all traditional (\vee - \wedge) fuzzy equivalence relations;

\mathfrak{B} - set of all bold (\vee - \wedge) fuzzy equivalence relations;

$\mathfrak{E}^0 = \mathfrak{B}^0$ - lattice of all crisp equivalence relations (partitions of X); $\{ij\}$ - atoms of the lattice \mathfrak{E}^0 , that is, partitions with single non-trivial equivalence class $\{ij\}$; note that $\{ij\}$'s form all closest to $\mathbf{0}$ vertexes of \mathcal{S} (in other words, vertexes of $V(\mathbf{0}, 1)$).

2. BASIC PROPERTIES OF $\hat{\mathfrak{E}}, \mathfrak{B}$

"Decomposition problem" for bold equivalences was initiated by the discovering of an inclusion $\hat{\mathfrak{E}} \subseteq \mathfrak{B}$.

PROPOSITION 0. Primary properties of $\mathfrak{E}^0, \mathfrak{E}, \hat{\mathfrak{E}}, \mathfrak{B}$.

(i) both $\hat{\mathfrak{E}}$, and \mathfrak{B} are convex subsets of \mathcal{S} ;

(ii) $\hat{\mathfrak{E}} = \mathfrak{E}^0$ - any convex combination of fuzzy \vee - \wedge equivalence relations can be represented as convex combination of crisp equivalences;

(iii) $\mathfrak{E} = \mathfrak{E}^0 \subseteq \mathfrak{B}$ - crisp equivalences form all extremal points of \mathfrak{E} , which are also extremal points (not all!) of \mathfrak{B} ■

PROPOSITION 1. With $n \leq 3$, $\hat{\mathfrak{E}} = \mathfrak{B}$ ■

With $n \geq 4$, $\hat{\mathfrak{E}}$ and \mathfrak{B} do not coincide. So, the main problem is

(P1) Find decomposability criterion.

However, since $\hat{\mathfrak{E}}$ and \mathfrak{B} are convex subsets of \mathcal{Y} , several problems in the spirit of "convex analysis" can also be stated:

(P2) Investigate location of $\hat{\mathfrak{E}}$ in \mathfrak{B} ;

(P3) Describe all extremal points of \mathfrak{B} ;

(P4) Find most distant from $\hat{\mathfrak{E}}$ extremal points of \mathfrak{B} .

We start with P2-P3 to motivate possible approach to P1.

First, let us study dimensions of $\hat{\mathfrak{E}}$, \mathfrak{B} . Owing to inclusions $\hat{\mathfrak{E}} \subseteq \mathfrak{B} \subseteq \mathcal{Y}$, there formally exist four variants:

(a) $\dim(\hat{\mathfrak{E}}) < \dim(\mathfrak{B}) < \dim(\mathcal{Y})$;

(b) $\dim(\hat{\mathfrak{E}}) < \dim(\mathfrak{B}) = \dim(\mathcal{Y})$;

(c) $\dim(\hat{\mathfrak{E}}) = \dim(\mathfrak{B}) < \dim(\mathcal{Y})$;

(d) $\dim(\hat{\mathfrak{E}}) = \dim(\mathfrak{B}) = \dim(\mathcal{Y})$.

PROPOSITION 2. (dimension of $\hat{\mathfrak{E}}$, \mathfrak{B}).

(i) Variant (d) is in force; hence, $\hat{\mathfrak{E}}$ and \mathfrak{B} are "bodies" in \mathcal{Y} .

(ii) $\hat{\mathfrak{E}}$ contains unit neighborhood of $\mathbf{0}$ $V(\mathbf{0}, 1) = \{\mathbf{0} \cup \{\hat{1}_j\}\}$; maximal cube, contained in this neighborhood, is $[\mathbf{0}, \mathbf{C}]$ (\mathbf{C} - for the center of simplex $\{\{\hat{1}_j\}\}$), $\mathbf{C} = \frac{N-1}{N} \cdot \mathbf{0} + \frac{1}{N} \cdot \mathbf{I}$.

(iii) $\hat{\mathfrak{E}}$ contains "central domain" of \mathfrak{B} , i.e. a neighborhood of the "diagonal" $\{\mathbf{C}_\alpha = \alpha \cdot \mathbf{0} + (1-\alpha) \cdot \mathbf{I}\}$; thus, for any \mathbf{C}_α , $V(\mathbf{C}_\alpha, \alpha/2) \subset \hat{\mathfrak{E}}$.

(iv) \mathfrak{B} contains the whole cube $[\mathbf{0}, \frac{1}{2} \cdot \mathbf{0} + \frac{1}{2} \cdot \mathbf{I}]$,

3. EXTREMAL NON-DECOMPOSABLE POINTS OF \mathfrak{B}

Let $i \in X$; consider all FRs, containing only the i -th nonzero row/column (except for the diagonal); say, for $i = 1$

$$E = \begin{vmatrix} 1 & \alpha_2 & \dots & \alpha_n \\ \alpha_2 & 1 & \dots & 0 \\ \vdots & 0 & 1 & \dots \\ \alpha_n & \dots & \dots & 1 \end{vmatrix}$$

These FRs form a $(n-1)$ -dimensional cube, which is denoted by $\mathcal{F}^1 = [0, \bigvee_{j \in J} \{ij\}]$.

Next, with $\mathbf{a} = \{\alpha_1, \dots, \alpha_{i-1}, \alpha_{i+1}, \dots, \alpha_n\} \in \tilde{\mathcal{F}}(X \setminus \{i\})$, set

$$E^1(\mathbf{a}) = \bigvee_{j \in J} \alpha_j \cdot \{ij\}.$$

PROPOSITION 3 (particular family of extremal non-decomposable points of \mathfrak{B}).

(i) With $3 \leq m \leq n-1$, centers of all m -dimensional sides of \mathcal{F}^1

$$C^{iJ} = E^1\left(\frac{1}{2} \chi_J\right)$$

($J \subseteq X \setminus \{i\}$, $m = |J| \geq 3$) are extremal points of \mathfrak{B} ; none of these FRs belongs to $\hat{\mathfrak{E}}$.

$$C^{iJ} = \begin{array}{c} J \\ \left[\begin{array}{cccccccc} 1 & 0 & \overbrace{1/2 \ 1/2 \ \dots 1/2}^J & 0 & \dots & 0 & & \\ 0 & 1 & & & & & & \\ 1/2 & & 1 & & & 0 & & \\ 1/2 & & & 1 & & & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 1/2 & & & & & 1 & & \\ 0 & & 0 & & & & 1 & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 0 & & & & & & & 1 \end{array} \right] \end{array}$$

(ii) The distance (in Hemming metric) between a center C^{iJ} , and the set of all decomposable bold equivalences

$$\rho_1(C^{iJ}, \hat{\mathfrak{E}}) = \frac{m}{2} - 1$$

(iii) Projection of C^{iJ} on $\hat{\mathfrak{E}}$ is not included in \mathcal{F}^1 ; it contains all FRs in $\hat{\mathfrak{E}}$, represented as

$$E = \sum_{j \in J} \lambda_j \{ij\} + \sum_{j,k \in J} \lambda_{jk} \{ijk\},$$

with λ_j, λ_{jk} satisfying two conditions:

$$\sum_j \lambda_j + \sum_{j,k} \lambda_{jk} = 1 \quad (1)$$

$$(\forall j) (\lambda_j + \sum_k \lambda_{jk} \leq 1/2) \quad (2)$$

Extremal points of the projection of C^{iJ} on $\hat{\mathfrak{E}}$ contain two families of FRs:

$$\frac{\{1k\} + \{11\}}{2} = \begin{matrix} & & & \begin{matrix} k & J & 1 \end{matrix} \\ & & & \overline{\hspace{10em}} \\ J & \begin{matrix} k \\ 1 \end{matrix} & \left[\begin{array}{cccccccc} 1 & 0 & 1/2 & 0 & \dots & 1/2 & \dots & 0 & 0 & \dots & 0 \\ 0 & 1 & & & & & & & & & & \\ 1/2 & & 1 & & & & & 0 & & & & \\ 0 & & & 1 & & & & & & & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 1/2 & & & & & & & 1 & & & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 0 & & & & & & & & 1 & & & \\ 0 & & & & & & & & & 1 & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 0 & & 0 & & & & & & & 1 & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 0 & & & & & & & & & & & 1 \end{array} \right. \end{matrix}$$

(1/2 - exactly on two places in J), and

$$\frac{\{1k1\} + \{1s\}}{2} = \begin{matrix} & & & \begin{matrix} k & 1 & J & s \end{matrix} \\ & & & \overline{\hspace{10em}} \\ J & \begin{matrix} k \\ 1 \\ s \end{matrix} & \left[\begin{array}{cccccccc} 1 & 0 & 1/2 & 1/2 & \dots & 1/2 & \dots & 0 & 0 & \dots & 0 \\ 0 & 1 & 1/2 & & & & & & & & & \\ 1/2 & 1/2 & 1 & & & & & 0 & & & & \\ 1/2 & & & 1 & & & & & & & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 1/2 & & & & & & & 1 & & & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 0 & & & & & & & & 1 & & & \\ 0 & & & & & & & & & 1 & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 0 & & 0 & & & & & & & 1 & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \\ 0 & & & & & & & & & & & 1 \end{array} \right. \end{matrix}$$

(iv) For $n=4$, $\mathcal{E}^0 \cup \{C^{1J}\}$ exhausts all extremal points of \mathfrak{B} , so that C^{1J} 's represent "most non-decomposable" bold equivalences ■

Proof of (i) is based on several simple propositions.

Denote by $\mathcal{E}^1 = \mathcal{E}^1_{\mathcal{F}^1}$, $\widehat{\mathcal{E}}^1 = \widehat{\mathcal{E}}^1_{\mathcal{F}^1}$, $\mathfrak{B}^1 = \mathfrak{B}^1_{\mathcal{F}^1}$ sets of all traditional fuzzy equivalences, convex combinations of these equivalences and bold fuzzy equivalences, contained in \mathcal{F}^1 . Let $\mathbf{a} = \{\alpha_1, \dots, \alpha_{i-1}, \alpha_{i+1}, \dots, \alpha_n\} \in \widetilde{\mathcal{T}}(X \setminus \{i\})$; set $E^1(\mathbf{a}) = \bigvee \alpha_j \cdot \{1j\}$. Clearly, $\|E^1(\mathbf{a})\|_1 = \|\mathbf{a}\|_1$.

LEMMA 1 (characterization of $\widehat{\mathcal{E}}^1$). $\widehat{\mathcal{E}}^1 = \{ E^1(\mathbf{a}) \mid \|\mathbf{a}\|_1 \leq 1 \}$ ■

LEMMA 2 (characterization of \mathfrak{B}^1).

$$\mathfrak{B}^1 = \{ E^1(\mathbf{a}) \mid (\forall k, l \in X \setminus \{i\})(k \neq l \Rightarrow \alpha_k \wedge \alpha_l = 0) \}$$
 ■

LEMMA 3. For all $E^1(a) \in \mathfrak{B}^1$, $\|a\|_1 \leq \frac{1}{2} |\text{supp}(a)|$; equality is only for $a = (1/2, \dots, 1/2)$ ■

Proof of (ii), (iii) is complicated, though routine.

For (iv), straightforward search of all extremal points of \mathfrak{B} was done using special software tools ■

4. t-TRANS-CONVEXITY

Returning to P1, one can set a question: in what terms must we formulate decomposability criterion? We cannot expect the "symmetric polynomial" answer: indeed,

$$C^{1\{2,3,4\}} = \begin{vmatrix} 1 & 1/2 & 1/2 & 1/2 \\ 1/2 & 1 & 0 & 0 \\ 1/2 & 0 & 1 & 0 \\ 1/2 & 0 & 0 & 1 \end{vmatrix}$$

is non-decomposable, whereas

$$\begin{vmatrix} 1 & 1/2 & 1/2 & 0 \\ 1/2 & 1 & 1/2 & 0 \\ 1/2 & 1/2 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix}$$

contains the same number of 1/2's and is represented as $1/2 \cdot 0 + 1/2 \cdot \{123\} \in \hat{\mathfrak{E}}$. Hence, any symmetric polynomial $\pi(\{e_{1j}\})$ does not distinguish between these two relations, $\pi(C^{1\{2,3,4\}}) = \pi(1/2 \cdot 0 + 1/2 \cdot \{123\})$.

Attempting to find answer in "algebraic" style, let us characterize $\hat{\mathfrak{E}}$, and \mathfrak{B} in terms of t-norms. Denote by \mathfrak{E}_t set of all \vee -t-equivalences, that is, reflexive, symmetric and \vee -t-transitive FRs (thus, $\mathfrak{E} = \mathfrak{E}_\wedge$, $\mathfrak{B} = \mathfrak{E}_\wedge$). Call a t-norm t' **t-trans-convex** iff $\hat{\mathfrak{E}}_t \subseteq \mathfrak{E}_{t'}$. Trans-convexity is described in a simple way.

PROPOSITION 4. t' is t-trans-convex iff for any $x, y \in [0,1]^2$, $\lambda \in [0,1]$,

$$t'(\lambda x + (1-\lambda)y) \leq \lambda t(x) + (1-\lambda)t(y)$$

or, equivalently, $t'(\{\hat{x}, \hat{y}\}) \leq \{t(x), t(y)\}$ (in particular, $t' \leq t$) ■

Clearly, if t' is itself convex, $t'(\{\hat{x}, \hat{y}\}) \leq \{t'(x), t'(y)\}$, then, for any $t \geq t'$ (that is, for any t-norm in the interval $[t', \wedge]$), t' is t-trans-convex. Within this approach, Lukasiewicz's t-norm has one more characterization.

PROPOSITION 5. \wedge is maximal convex t-norm ■

Define a **trans-convex hull** of any \mathfrak{E}_t

$$\mathfrak{X}(\mathfrak{E}_t) = \bigcap \mathfrak{E}_{t'},$$

t' is t-trans-convex

(obviously, $\widehat{\mathfrak{E}}_t \subseteq \mathfrak{X}(\mathfrak{E}_t)$).

PROPOSITION 6. $\mathfrak{X}(\mathfrak{E}) = \mathfrak{E}$; even more, for any $t \in [\wedge, \wedge]$, $\mathfrak{X}(\mathfrak{E}_t) = \mathfrak{E}$ ■

This is, in fact, one more unsuccessful attempt to describe decomposability conditions - for any collection T of t-norms, $\widehat{\mathfrak{E}}$ cannot be represented in the form $\bigcap_{t' \in T} \mathfrak{E}_{t'}$.

5. COMBINATORIAL DECOMPOSABILITY CONDITIONS

So, let us try to find more "combinatorial" conditions. Let $E \in \mathfrak{E}$. Denote by $Q(E)$ the set of all crisp equivalences, not exceeding (that is, contained in) crisp relation $E_{>0}$:

$$Q(E) = [0, E_{>0}] \cap \mathfrak{E}^0,$$

by $\mathfrak{E}(E)$ - the set of all coverings of $E_{>0}$ by of crisp equivalences (except for the atoms $\{1j\}$), contained in $Q(E)$:

$$\mathfrak{E}(E) = \{ \mathfrak{X} \subseteq Q(E) \mid (\text{no } E' \in \mathfrak{X} \text{ is atom}) \ \& \ (\bigvee_{E' \in \mathfrak{X}} E' = E_{>0}) \}$$

With any $\mathfrak{X} \in \mathfrak{E}(E)$, define **FR** $M(\mathfrak{X})$ as "arithmetical mean" of all **CR**'s in \mathfrak{X} :

$$M(\mathfrak{X}) = \sum_{E' \in \mathfrak{X}} E' / |\mathfrak{X}|.$$

Using these notations, a necessary, and a sufficient condition of decomposability can be formulated.

PROPOSITION 7 (a necessary condition for decomposability).

$$E \in \widehat{\mathfrak{E}} \Rightarrow (\exists \mathfrak{X} \in \mathfrak{E}(E)) (|\mathfrak{X}| (\|M(\mathfrak{X})\|_1 - 1) \geq \|E\|_1 - 1)$$

(in particular, this condition is satisfied for any E with $\|E\|_1 \leq 1$) ■

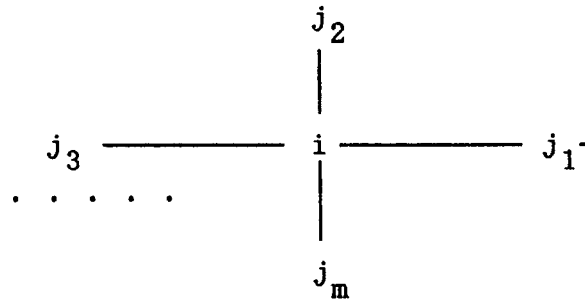
PROPOSITION 8 (a sufficient condition for decomposability).

$$\frac{M(\mathfrak{X})}{\|M(\mathfrak{X})\|_1 - 1} \subseteq \frac{E}{\|E\|_1 - 1} \Rightarrow E \in \widehat{\mathfrak{E}}$$

(here, both $\frac{M(\mathfrak{X})}{\|M(\mathfrak{X})\|_1 - 1}$, and $\frac{E}{\|E\|_1 - 1}$ are real-valued relations - not necessarily FRs, since their elements may exceed 1; nevertheless, inclusion \subseteq is used in the same meaning as in fuzzy case) ■

Both the PROPOSITION 7, and the PROPOSITION 8 can be written in a simpler fashion. However, using $M(\mathfrak{X})$ has certain advantages, emphasizing the "probabilistic" character of $\hat{\mathfrak{E}}$ - any $E \in \hat{\mathfrak{E}}$ can be considered as expected value of certain probability distribution on \mathfrak{E}^0 . In these terms, $M(\mathfrak{X})$ is the center of the simplex of all distributions with a given support $\mathfrak{X} \subseteq \mathfrak{E}^0$.

Decomposability condition in PROPOSITION 7 is closely related to the above example given in PROPOSITION 3. Indeed, for $J \subseteq X \setminus \{1\}$, $|J|=m \geq 3$, $(C^{1J})_{>0}$ is a m-star



Clearly, $Q(E^1(a)) = \{ \{ij\} \mid j \in J \}$, and $\mathfrak{E}(E^1(a)) = \emptyset$, so that left-hand expression in the inequality, given in 7, is zero, which means $\|E^1(a)\|_1 \leq 1$ (cf. LEMMA 1).

In fact, all previous results are due to "small", or "rarefied" FRs. Can we reduce an arbitrary bold equivalence to the rarefied one (with $E_{>0}$ being considerably less than I). Define $e_\wedge = \wedge e_{1j}$, and suppose $e_\wedge > 0$ ($\Leftrightarrow E_{>0} = I$). Obviously, if $E \in \mathfrak{B}$ and $E_{>0} = I$ then $E_0 = (E - e_\wedge \cdot I) / (1 - e_\wedge) \in \mathfrak{B}$.

However, this subtraction doesn't preserve decomposability (that is, $E \in \hat{\mathfrak{E}}$ must not imply $E_0 \in \hat{\mathfrak{E}}$). A simple counter-example is for $n=5$, $E^{1(2)} \triangleq \frac{1}{6} \sum_{j,k} \{ijk\}$; thus, for $i = 1$,

$$E^{1(2)} = \begin{vmatrix} 1 & 1/2 & 1/2 & 1/2 & 1/2 \\ 1/2 & 1 & 1/6 & 1/6 & 1/6 \\ 1/2 & 1/6 & 1 & 1/6 & 1/6 \\ 1/2 & 1/6 & 1/6 & 1 & 1/6 \\ 1/2 & 1/6 & 1/6 & 1/6 & 1 \end{vmatrix}, \text{ and}$$

$$E_0 = (E - 1/6 \cdot I) / (5/6) = \begin{vmatrix} 1 & 2/5 & 2/5 & 2/5 & 2/5 \\ 2/5 & 1 & 0 & 0 & 0 \\ 2/5 & 0 & 1 & 0 & 0 \\ 2/5 & 0 & 0 & 1 & 0 \\ 2/5 & 0 & 0 & 0 & 1 \end{vmatrix} \text{ is non-decomposable.}$$

There exist other possibilities - say, both E and E_0 may well be non-decomposable. For instance, let $i \in X$, $J \subseteq X \setminus \{i\}$, $|J|=m$, $\varepsilon < \frac{\frac{m}{2} - 1}{N-m}$. Set $C^{iJ} = (1-\varepsilon) \cdot C^{iJ} + \varepsilon \cdot I$. Clearly, $(C_\varepsilon^{iJ}) = C^{iJ}$, and

$$\|C^{iJ} - C_\varepsilon^{iJ}\|_1 = (N-m) \cdot \varepsilon < \frac{m}{2} - 1$$

It follows from **PROPOSITION 3** (i), (ii), that none of C_ε^{iJ} , $(C_\varepsilon^{iJ})_0$ is decomposable).