

Fuzzy Matching Approach to Target Identification

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Abstract

The method of identifying radar target in frequency domain in terms of fuzzy near-tude is presented. The process of backscatter data fitting is described firstly, and then the matching method based on fuzzy near-tude is given. The experiments are done by the use of scattering data provided by Dr. D. L. Moffatt. The results obtained show that the identifier in this paper has good performance of target identifications.

Key words— Fuzzy near-tude, Fuzzy match, Radar target, Target identification, Backscatter data.

1. Introduction

This paper is based on the impulse response concept advanced by Kennaugh and Cosgriff in 1958 and formalized by Kennaugh and Moffatt in 1965 and also the fuzzy near-tude concept which will be defined later. It has been demonstrated that discrete spectral scattering data spanning the Rayleigh and low resonance ranges of the scatter define the gross physical properties (size, shape, and composition) of the target, and that the transient response waveform defined by Rayleigh and low resonance range data can be approximated by finite exponential sum. Thus rational function approximations were postulated for the scattering transfer function in the Rayleigh and low resonance ranges of the scatter. This suggested that characterization of the scatter by a few complex natural resonant frequencies modeled as simple poles in the transfer function.

Once the poles are known, they may be used to classify or identify an object from its complex resonances. The

problem in any case is to determine how we might use pole sets to classify and identify objects, since its pole set underlies all of an object's electromagnetic behavior. Because the poles appear in both the time- and frequency-domain response of an object, it might be anticipated classification and identification could be performed in either domain. That is indeed the case. One approach for doing this using transient data has been developed by Mains and Moffatt in 1975.

In this paper we are interested in using spectral or frequency-domain information. Firstly, the fitting process of scattering data is described. Then an algorithm for measuring the match degree between the backscatter data and fitting data is derived using fuzzy nearitude. Finally, experiments are made in assessing the performance of the identifications.

2. Frequency-Domain Data Fitting And Fuzzy Decision

Suppose a linear polarized plane wave, with x -directed electric field

$$\vec{E}_i = \hat{x} E_0 \exp(j(\omega t - kz)) \quad (1)$$

is incident upon an object at the origin. Here, ω is radiation frequency, $k = \omega/c$ is the wave number and z is the direction of propagation. The x -polarized backscattered field, \vec{E}_s , at a large distance r along the negative z axis is given as

$$\vec{E}_s = \hat{x} \exp(j(\omega t - kr)) G(j\omega) E_0 / 2\sqrt{\pi} r. \quad (2)$$

This defines $G(j\omega)$, the object's frequency response for backscattering at a specified aspect angle. With this definition, the power cross-section of the scatter, denoted as σ_s , is given by the equation

$$\sigma_s = 4\pi r^2 |\vec{E}_s|^2 / |E_0|^2 = |G(j\omega)|^2. \quad (3)$$

On another hand, we have:

$$|G(j\omega)|^2 = G(j\omega) G^*(j\omega) = G(s) G(-s) \Big|_{s=j\omega} = B(-\omega^2) A(-\omega^2)^{-1},$$

Where $A(\cdot)$ and $B(\cdot)$ are polynomials. So, letting $x = -s^2$, we have

$$\sigma_s = |G(j\omega)|^2 = B(x)/A(x) = \frac{\sum_{i=0}^{N-2} b_i x^i}{(1 + \sum_{i=1}^N a_i x^i)}. \quad (4)$$

Here, $\{b_i\}_{i=0}^{N-2}$ are called zero coefficients, and $\{a_i\}_{i=1}^N$ pole coefficients.

Suppose that scattering data $\{\sigma_i\}_{i=1}^L$ at L (even number) frequencies are observed and the pole coefficients $\{a_{ij}\}_{j=1}^L$ ($i=1, 2, \dots, m$) of m interested targets are obtained, let:

$$(1 + \sum_{j=1}^N a_{ij} x_1^j) \sigma_{i1} = \sigma_{i1} \quad (l=1, 2, \dots, L, i=1, 2, \dots, m),$$

we obtain:

$$(\&) \quad \sum_{j=0}^{N-2} b_{ij} x_1^j = \sigma_{i1} \quad (l=1, 3, \dots, L-1, i=1, 2, \dots, m).$$

For given i , the overdetermined equation system (&) can be solved by the use of least-square methods. Assuming the least-square solution is $(b_{i0}^!, b_{i1}^!, \dots, b_{iN-2}^!)^T$ ($i=1, 2, \dots, m$), the fitting data are calculated as follows:

$$\sigma_{i1} = \frac{\sum_{j=0}^{N-2} b_{ij}^! x_1^j}{(1 + \sum_{j=1}^N a_{ij} x_1^j)}. \quad (i=1, 2, \dots, m, l=2, 4, \dots, L)$$

It is necessary to measure the similarity between fitting data and scattering data for performing target identification. We first define m fuzzy subsets R_i of $E_L = \{(\sigma_2, \sigma_4, \dots, \sigma_L) \mid \sigma_l > 0, l=2, 4, \dots, L\}$ ($i=1, 2, \dots, m$). The elements of R_i are scattering data from the i th target "possibly". Once the membership functions $u_{R_i}(\cdot)$ of R_i ($i=1, 2, \dots, m$) which describe the matching degree of $\{\sigma_{i1}\}$ and $\{\sigma_l\}$ have been obtained, we make a decision as follows:

$$H_i \mid u_{R_i}(\{\sigma_i\}) = \max_{j=1}^m u_{R_j}(\{\sigma_i\}), \quad (5)$$

where H_i means the scatter is the i th interested target.

3. Fuzzy Matching Algorithm

It follows from eq.(5) that the matching algorithm is a key part of target identifications. The study here is based on the fuzzy nearitude concept.

Definition 1: Let E_L be a universe, $\mathcal{F}(E_L)$ the family of all fuzzy subsets of E_L . The nearitude on $\mathcal{F}(E_L)$ is a map from $\mathcal{F}(E_L) \times \mathcal{F}(E_L)$ to $[0, 1]$:

$$\rho : \mathcal{F}(E_L) \times \mathcal{F}(E_L) \longrightarrow (0,1),$$

which is satisfied with (i) $\forall A, B \in \mathcal{F}(E_L), \rho(A, B)$ takes maximum value when $A=B$ and minimum when $A=0$ and $B=1$; (ii) $\forall A, B \in \mathcal{F}(E_L), \rho(A, B) = \rho(B, A)$; (iii) $\forall A, B, C \in \mathcal{F}(E_L)$, if $A \subseteq B \subseteq C$ or $A \supseteq B \supseteq C$, then $\rho(A, B) \geq \rho(A, C)$.

It can be seen from definition 1 that the nearitude $\rho(., .)$ is actually a binary fuzzy relation in $\mathcal{F}(E_L)$ satisfied with (i), (ii), (iii). It reflects the matching degree between fuzzy subsets of E_L .

$\forall A, B \in \mathcal{F}(E_L)$, let $A \circ B = \sup_{x \in E_L} (u_A(x) \wedge u_B(x))$ and $A \oplus B = \inf_{x \in E_L} (u_A(x) \vee u_B(x))$, we have:

$$\text{Lemma 1: } \forall A \in \mathcal{F}(E_L), A \circ A = \sup_{B \in \mathcal{F}(E_L)} A \circ B, A \oplus A = \inf_{B \in \mathcal{F}(E_L)} A \oplus B.$$

Lemma 2: If $B \supseteq A$ then $A \circ B = \bar{A}$; if $B \subseteq A$ then $A \oplus B = \underline{A}$, where $\bar{A} = \sup_{x \in E_L} u_A(x)$ and $\underline{A} = \inf_{x \in E_L} u_A(x)$.

From lemma 1 and 2 we have:

Theorem 1: Let E_L be a universe, ρ a map from $\mathcal{F}(E_L) \times \mathcal{F}(E_L)$ to $[0,1], \forall A, B \in \mathcal{F}(E_L)$,

$$\rho(A, B) = (A \circ B) \vee (1 - (A \oplus B)). \tag{6}$$

Then, ρ is a nearitude on $\mathcal{F}(E_L)$.

Apparently, if E_L has only one element, then

$$\rho(A, B) = (u_A(x) \wedge u_B(x)) \vee (\overline{u_A(x) \wedge u_B(x)}). \tag{7}$$

The first thing is to normalize the scattering data and fitting data:

$\sigma'_{ij} = (\sigma_{ij} - \sigma_i^{\min}) / (\sigma_i^{\max} - \sigma_i^{\min}), \sigma'_j = (\sigma_j - \sigma^{\min}) / (\sigma^{\max} - \sigma^{\min})$, where $\sigma_i^{\min} = \min_j \sigma_{ij}, \sigma^{\max} = \max_j \sigma_j$ and so on ($i=1, \dots, m, j=2, 4, \dots, L$).

From eq.(7) we define: $\rho_{ij} = (\sigma'_{ij} \wedge \sigma'_j) \vee (\overline{\sigma'_{ij} \wedge \sigma'_j})$ ($i=1, 2, \dots, m, j=2, 4, \dots, L$). Finally the match may be written by

$$Ne_i = \sum_{j=1}^{L/2} \rho_{i, 2j}, \quad i=1, 2, \dots, m. \tag{8}$$

The membership functions of R_i are:

$$u_{B_i}(\sigma_j) = Ne_i / \sum_{i=1}^m Ne_i, \quad i=1, 2, \dots, m. \tag{9}$$

4. Experiments And Conclusions

In assessing the performance of identifier presented in this paper, experiments are made for three different kind of targets. They are medium sphere ($d=1.59m, \epsilon_r=2.208$), prolate spheroid (major axis=1.59, minor axis=0.795m) and cube (edge length=0.682m). Ten times are assumed in the process of identifications for each target. Fig.1, Fig.2 and Fig.3 show the fitting data of prolate spheroid when three different pole coefficients are applied. The experiments results are tabulated in table 1 which shows the performance of the identifier is good. This procedure allows an identification to be made without the necessity of finding the poles from scattering data. Because of using fuzzy nearitude as a measure of matching degrees between fitting data and scattering data, the matching process of the identifier is similar to brain's one. Thus the activity of the identifier is increased largely.

5. References

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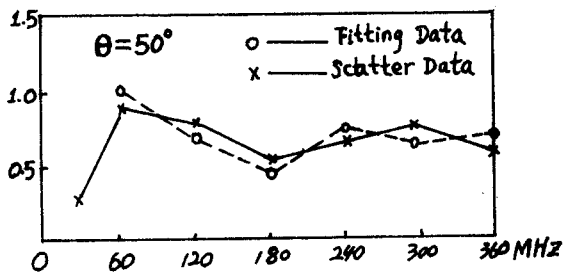


Fig.1 The Same pole set

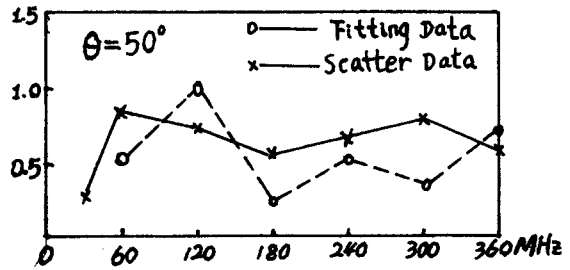


Fig.2 The different pole set

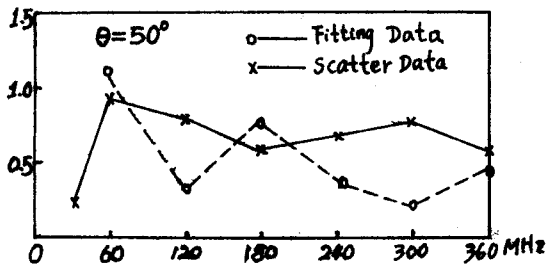


Fig.3 The different pole set

ident. / resul.	med. sphe.	prola. spher.	Cube	Correct rate
medium sphere	10	0	0	1
prolate spheroid	0	9	1	0.9
Cube	0	1	9	0.9

Table 1 Results of identification